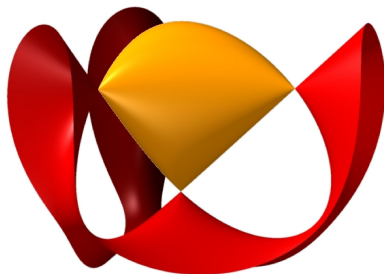
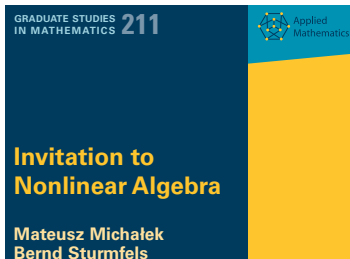


BEYOND LINEAR ALGEBRA

Bernd Sturmfels

MPI Leipzig and UC Berkeley



International Congress of Mathematicians,
July 8, 2022

Undergraduate Linear Algebra

All undergraduate students learn about *Gaussian elimination*, a general method for solving linear systems of algebraic equations:

Input:

$$\begin{aligned}x + 2y + 3z &= 5 \\7x + 11y + 13z &= 17 \\19x + 23y + 29z &= 31\end{aligned}$$

Output:

$$\begin{aligned}x &= -35/18 \\y &= 2/9 \\z &= 13/6\end{aligned}$$

Solving very large linear systems is central to applied mathematics.

Undergraduate Non-Linear Algebra

Lucky undergraduate students also learn about *Gröbner bases*, a general method for non-linear systems of algebraic equations:

Input:

$$x^2 + y^2 + z^2 = 2$$

$$x^3 + y^3 + z^3 = 3$$

$$x^4 + y^4 + z^4 = 4$$

Output:

$$3z^{12} - 12z^{10} - 12z^9 + 12z^8 + 72z^7 - 66z^6 - 12z^4 + 12z^3 - 1 = 0$$

$$4y^2 + (36z^{11} + 54z^{10} - 69z^9 - 252z^8 - 216z^7 + 573z^6 + 72z^5 - 12z^4 - 99z^3 + 10z + 3) \cdot y + 36z^{11} + 48z^{10} - 72z^9 - 234z^8 - 192z^7 + 564z^6 - 48z^5 + 96z^4 - 96z^3 + 10z^2 + 8 = 0$$

$$4x + 4y + 36z^{11} + 54z^{10} - 69z^9 - 252z^8 - 216z^7 + 573z^6 + 72z^5 - 12z^4 - 99z^3 + 10z + 3 = 0$$

Numerical homotopy methods solve polynomial systems reliably.

3264 CONICS IN A SECOND

Paul Breiding
Bernd Sturmfels
Sascha Timme



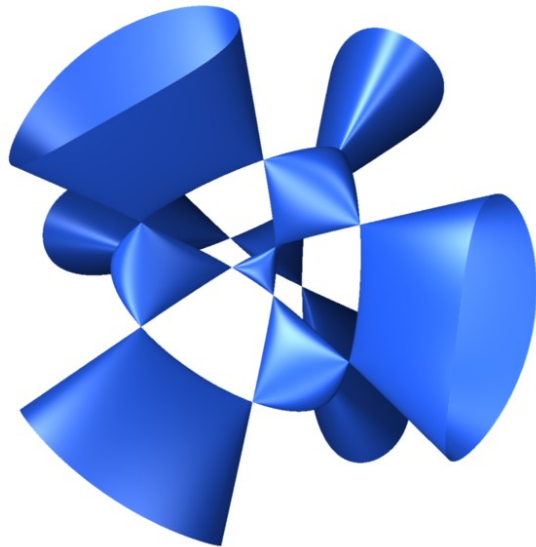
In 1848 Jakob Steiner asked
«**How many** conics are tangent to **five** conics?»
In 2019 we ask
«**Which** conics are tangent to **your five** conics?»

Curious to know the answer?
Find out at:

juliahomotopycontinuation.org/do-it-yourself/

Nonlinear Shapes

Many models in the sciences and engineering are solution sets of polynomial equations. Such a set is an **algebraic variety** $X \subset \mathbb{R}^n$.



Nearest Points on Varieties

Fix a variety X in \mathbb{R}^n , ideal $I_X = \langle f_1, \dots, f_k \rangle$, and $c = \text{codim}(X)$.

The $k \times n$ Jacobian matrix $\mathcal{J} = (\partial f_i / \partial x_j)$ has rank $\leq c$ on X .

A point $x \in X$ is *nonsingular* if rank = c .

Assumption: nonsingular real points are Zariski dense in X .

The following optimization problem arises in many applications:

Given a data point $u \in \mathbb{R}^n$, compute the distance to the model X .

We seek x^* in X that is closest to u .

The answer depends on the metric. We begin with

The Euclidean distance (ED) problem:

$$\text{minimize } \sum_{i=1}^n (x_i - u_i)^2 \text{ subject to } x \in X.$$

Euclidean Distance Degree

The *augmented Jacobian* is the $(k + 1) \times n$ matrix with the extra row $(x_1 - u_1, \dots, x_n - u_n)$ atop the Jacobian matrix \mathcal{J} .

Form its ideal of $(c + 1) \times (c + 1)$ minors, add I_X , and saturate by the $c \times c$ minors of \mathcal{J} . This results in the *critical ideal* $\mathcal{C}_{X,u}$.

This defines the set of critical points of the ED problem. For random data u , this set is finite and contains the solution x^* ,
provided x^* is a nonsingular point of X .

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provided x^* is a nonsingular point of X .

The *ED degree* of X is the number of complex zeros of $\mathcal{C}_{X,u}$. This measures the difficulty of solving the ED problem for the model X .

[Draisma, Horobeț, Ottaviani, St, Thomas, 2016]

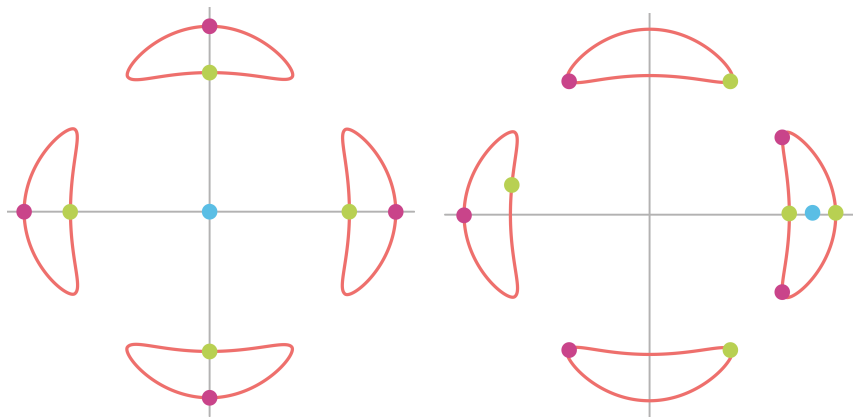
Proposition

If f_1, \dots, f_k have degrees $d_1 \geq \dots \geq d_k$ then

$$\text{EDdegree}(X) \leq d_1 d_2 \cdots d_c \cdot \sum_{i_1 + i_2 + \cdots + i_c \leq n - c} (d_1 - 1)^{i_1} (d_2 - 1)^{i_2} \cdots (d_c - 1)^{i_c}.$$

Trott Curve

If X is a quartic curve in \mathbb{R}^2 then $\text{EDdegree}(X) = 16$. Not all critical points are real. For example, consider the *Trott curve*:



$$144(x^4 + y^4) - 225(x^2 + y^2) + 350x^2y^2 + 81 = 0$$

Space Curves

Fix $n = 3$ and X a curve defined by general polynomials p, q of degrees d_1, d_2 in x, y, z . The augmented Jacobian matrix is

$$\mathcal{AJ} = \begin{pmatrix} x - u_1 & y - u_2 & z - u_3 \\ \partial p / \partial x & \partial p / \partial y & \partial p / \partial z \\ \partial q / \partial x & \partial q / \partial y & \partial q / \partial z \end{pmatrix}.$$

For random data $u \in \mathbb{R}^3$, the ideal $\mathcal{C}_{X,u} = \langle p, q, \det(\mathcal{AJ}) \rangle$ has $d_1 d_2 (d_1 + d_2 - 1)$ zeros in \mathbb{C}^3 . This is the **ED degree** of X .

Proposition

If X is a general smooth curve of **degree d** and **genus g** in \mathbb{R}^n then

$$\text{EDdegree}(X) = 3d + 2g - 2.$$

Curve has degree $d = d_1 d_2$ and genus $g = \frac{1}{2}(d_1^2 d_2 + d_1 d_2^2) - 2d_1 d_2 + 1$.

General Formula

Theorem

If $X \subset \mathbb{R}^n$ satisfies $\bullet \bullet \bullet$ then $EDdegree(X)$ equals the sum of the *polar degrees* of the projective closure of X in \mathbb{P}^n .

Hypothesis $\bullet \bullet \bullet$ holds for all X after linear change of variables.

General Formula

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Hypothesis $\bullet \bullet \bullet$ holds for all X after linear change of variables.

Points h in the *dual space* $(\mathbb{P}^n)^\vee$ are hyperplanes in \mathbb{P}^n . Consider pairs (x, h) in $\mathbb{P}^n \times (\mathbb{P}^n)^\vee$ with $x \in X$ nonsingular and h tangent to X at x . Zariski closure is the *conormal variety* $N_X \subset \mathbb{P}^n \times (\mathbb{P}^n)^\vee$.

Facts: N_X is irreducible of $\dim n - 1$, $N_X = N_{X^\vee}$ and $(X^\vee)^\vee = X$.

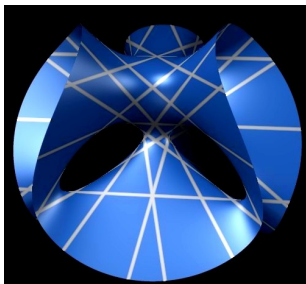
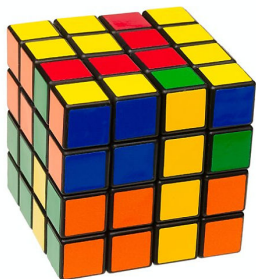
Polar degrees of X are coefficients of the cohomology class

$$[N_X] = \delta_1(X)s^n t + \delta_2(X)s^{n-1}t^2 + \cdots + \delta_n(X)st^n.$$

$$\text{in } H^*(\mathbb{P}^n \times (\mathbb{P}^n)^\vee, \mathbb{Z}) = \mathbb{Z}[s, t] / \langle s^{n+1}, t^{n+1} \rangle.$$

Interpretation

Polar degrees satisfy $\delta_i(X) = \#(N_X \cap (L_{n+1-i} \times L_i))$,
where $L_{n+1-i} \subset \mathbb{P}^n$ and $L_i \subset (\mathbb{P}^n)^\vee$ are general subspaces.



Example (General Surfaces in 3-space)

If X has degree d in \mathbb{P}^3 then N_X is a surface in $\mathbb{P}^3 \times (\mathbb{P}^3)^\vee$, with

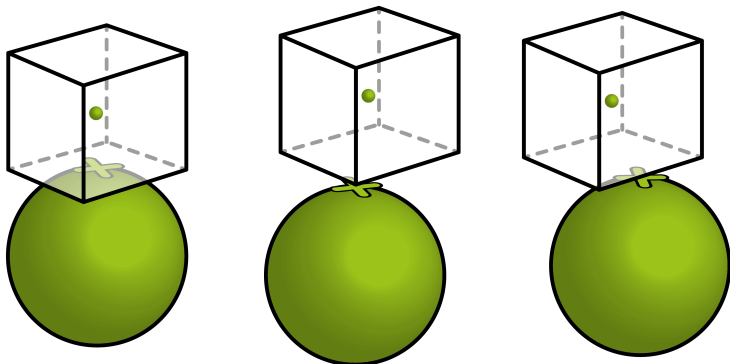
$$[N_X] = d(d-1)^2 s^3 t + d(d-1) s^2 t^2 + d s t^3.$$

The sum of polar degrees equals $\text{EDdegree}(X) = d^3 - d^2 + d$.

Polyhedral Norms

(Wasserstein)

Scale the *unit ball* until it meets the *variety* X .



Suppose the optimal face of the unit ball has codimension i .

Proposition

The polar degree $\delta_i(X)$ is the number of critical points of a linear form ℓ on $L \cap X$, where L is a general affine space of codimension $i - 1$ in \mathbb{R}^n .

State space $\{0, 1, \dots, n\}$. The probability simplex is

$$\Delta_n = \{p \in \mathbb{R}^{n+1} : p_0 + p_1 + \dots + p_n = 1 \text{ and } p_0, p_1, \dots, p_n > 0\}.$$

Model $X \subset \Delta$. **Data** $u \in \mathbb{N}^{n+1}$. The *log-likelihood function* is

$$\ell_u : \Delta_n \rightarrow \mathbb{R}, p \mapsto u_0 \cdot \log(p_0) + u_1 \cdot \log(p_1) + \dots + u_n \cdot \log(p_n).$$

The *ML degree* of X is the number of critical points of:

$$\text{Maximize } \ell_u(p) \text{ subject to } p \in X.$$

Example

If $n = 3$ and X is our curve $\{p = q = 0\}$ then

$$\text{ML degree}(X) = d_1 d_2 (d_1 + d_2 + 1).$$

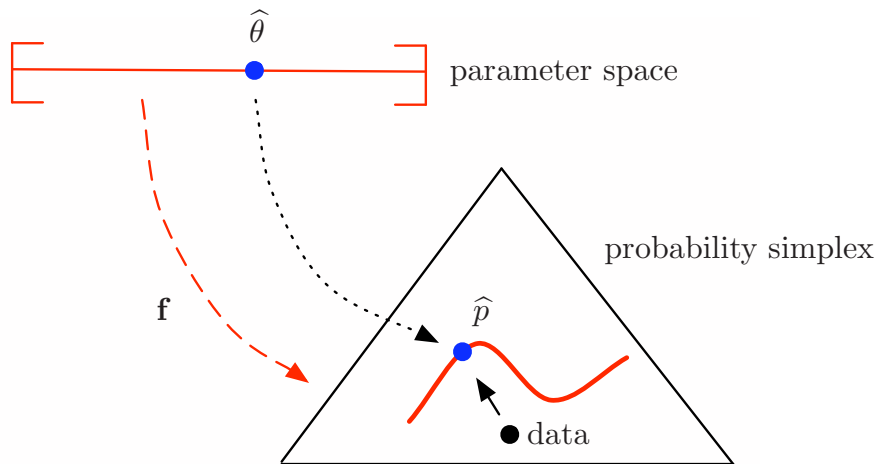


Fig. 3.2. The geometry of maximum likelihood estimation.

Euler Characteristic

View the model X in the complex projective space \mathbb{P}^n , and let

$$X^\circ = X \setminus \left\{ p_0 p_1 \cdots p_n \left(\sum_{i=0}^n p_i \right) = 0 \right\}.$$

Theorem

Suppose the *very affine variety* X° is non-singular.

The ML degree of the model X equals the signed Euler characteristic $(-1)^{\dim(X)} \cdot \chi(X^\circ)$ of the manifold X° .

polar degrees for ED \longleftrightarrow Euler characteristic for MLE

Theorem (Huh, Duarte-Marigliano-St)

If the model X has ML degree one, then each coordinate of p is an alternating product of linear forms in u with positive coefficients.

The *CEGM model*, due to Cachazo et al., is the space of m points in general position in \mathbb{P}^{k-1} :

$$X^\circ = \text{Gr}(k, m)^\circ / (\mathbb{C}^*)^m.$$

The data u are the **Mandelstam invariants**.

Proposition

X° is very affine; coordinates are $k \times k$ minors of

$$\begin{bmatrix} 0 & 0 & 0 & \dots & 0 & (-1)^k & 1 & 1 & 1 & \dots & 1 \\ 0 & 0 & 0 & \dots & (-1)^{k-1} & 0 & 1 & x_{1,1} & x_{1,2} & \dots & x_{1,m-k-1} \\ \vdots & \vdots & \vdots & \ddots & \vdots & \vdots & \vdots & \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & -1 & \dots & 0 & 0 & 1 & x_{k-3,1} & x_{k-3,2} & \dots & x_{k-3,m-k-1} \\ 0 & 1 & 0 & \dots & 0 & 0 & 1 & x_{k-2,1} & x_{k-2,2} & \dots & x_{k-2,m-k-1} \\ -1 & 0 & 0 & \dots & 0 & 0 & 1 & x_{k-1,1} & x_{k-1,2} & \dots & x_{k-1,m-k-1} \end{bmatrix}$$

Theorem

For $k = 2$, the ML degree equals $(m-3)!$ for all $m \geq 4$.

For $k = 3$ and $m = 5, 6, 7, 8, 9$, it is 2, 26, 1272, 188112, 74570400.

For $k = 4$, $m = 8$ it equals 5211816.

Likelihood Geometry

(Gaussian Models)

Statistical model is a variety X in $\text{PD}_n \subset \text{Sym}_2(\mathbb{R}^n)$. MLE means:

Maximize $\Sigma \mapsto \log \det \Sigma^{-1} - \text{trace}(\mathbf{S} \Sigma^{-1})$ subject to $\Sigma \in X$.

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Linear Space of Symmetric Matrices $\mathcal{L} \subset \text{Sym}_2(\mathbb{R}^n)$ gives a model

$$X = \{\Sigma : \Sigma^{-1} \in \mathcal{L}\} = \{K^{-1} : K \in \mathcal{L}\}.$$

Proposition

Critical equations for *maximum likelihood estimation* are

$$K \in \mathcal{L} \text{ and } K\Sigma = \text{Id}_n \text{ and } \Sigma - \mathbf{S} \in \mathcal{L}^\perp.$$

The **ML degree** of \mathcal{L} is the number of complex critical points.

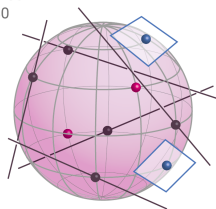
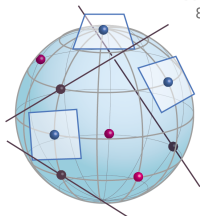
Example: For general LSSM with $n = 4$ we have

$k = \dim(\mathcal{L}) :$	2	3	4	5	6	7	8	9
ML degree :	3	9	17	21	21	17	9	3

Schubert Calculus



1	3	9	17	21	21	17	9	3	1
2	6	18	34	42	34	18	6	2	
4	12	36	68	68	36	12	4		
8	24	72	104	72	24	8			
16	48	112	112	48	16				
32	80	128	80	32					
56	104	104	56						
80	104	80							
92	92								
92									



Theorem (Michalek et al.)

The ML degree of \mathcal{L} is the number of quadrics in \mathbb{P}^{n-1} through $\binom{n+1}{2} - k$ general points and tangent to $k - 1$ general hyperplanes. For fixed k , this is a polynomial in n of degree $k - 1$.

Nonlinear Algebra meets Linear PDE

The following two things are the same:

- ▶ **Polynomials:**

$$X^2 - T^2 = (X - T)(X + T)$$

- ▶ Linear homogeneous **partial differential equations** with constant coefficients:

$$\phi_{xx}(x, t) - \phi_{tt}(x, t) = 0.$$

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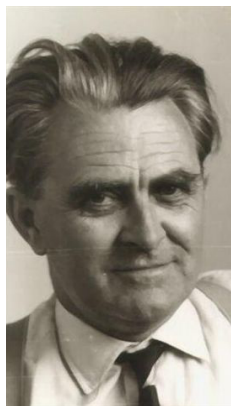
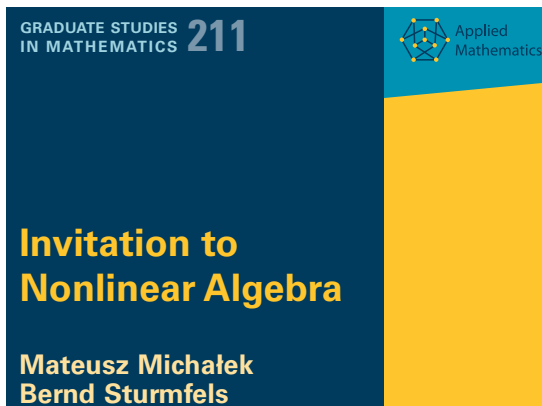
$$\phi_{xx}(x, t) - \phi_{tt}(x, t) = 0.$$

D'Alembert (1747): **General solution** is **superposition of traveling waves**:

$$\phi(x, t) = f(x + t) + g(x - t),$$

where f and g are twice differentiable functions, or **distributions**.

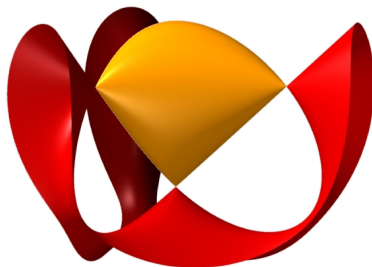
Current work: **any ideal in a polynomial ring, and any module.**



Theorem 3.27. *Let I be a zero-dimensional ideal in $\mathbb{C}[x_1, \dots, x_n]$, here interpreted as a system of linear PDEs. The space of holomorphic solutions has dimension equal to the degree of I . There exist nonzero polynomial solutions if and only if the maximal ideal $M = \langle x_1, \dots, x_n \rangle$ is an associated prime of I . In that case, the polynomial solutions are precisely the solutions to the system of PDEs given by the M -primary component $(I : (I : M^\infty))$.*

Cayley's Cubic Surface

This picture is the logo of the Nonlinear Algebra group at MPI Leipzig:



The **elliptope** is a PDE constraint for $\phi : \mathbb{R}^4 \rightarrow \mathbb{C}^3$:

$$\begin{bmatrix} \partial_1 & \partial_2 & \partial_3 \\ \partial_2 & \partial_1 & \partial_4 \\ \partial_3 & \partial_4 & \partial_1 \end{bmatrix} \bullet \begin{bmatrix} \phi_1 \\ \phi_2 \\ \phi_3 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

Quiz: What does the command `solvePDE` in `Macaulay2` tell us?

Epilog

Linear algebra is ubiquitous in the mathematical universe.

It plays a foundational role for models in the sciences and engineering; its numerical tools are a driving force for today's technologies. The power of linear algebra stems from **calculus**, i.e. our ability to **approximate nonlinear shapes by linear spaces**.

Yet, the world is nonlinear. Polynomials are a natural ingredient in mathematical models for the real world.

In our view, the nonlinear nature of a phenomenon should be respected as long as possible. We advocate against the practice of passing to a linear approximation right away.

Many Thanks for Listening