# Computation

- Most scientific problems do not have a closed form solution
- To solve them we must resort to computation and create an approximate solution
- To do this we create a numerical algorithm
- There are typically a myriad of algorithms
- Is there a way to tell whether algorithm is optimal or near optimal?
- How do we define optimal?
- Computations are not exact
- We cant even enter a real number into a computer without some error

n 2/20

ICM

Numerical Stability

# **Discrete Sensing**

- $\mathbf{p} \ x \in \mathbb{R}^N$  with N large
- We are able to ask n non-adaptive questions about x
- Question means inner product  $v \cdot x$  with  $v \in \mathbb{R}^N$  called sample
- Any such sampling is given by is an n × N matrix Φ : the entries in y = Φx are the answers to our questions



# **Optimal Matrices**

 We have only built Optimal Matrices using probabilistic methods

ICM - p.33/3

What can deterministic constructions give?

# **Optimal Matrices**

 We have only built Optimal Matrices using probabilistic methods

ICM - p.33/3

- What can deterministic constructions give?
- Needs a precise formulation

# **Optimal Matrices**

- We have only built Optimal Matrices using probabilistic methods
- What can deterministic constructions give?
- Needs a precise formulation
- We can not prove high performance for deterministic constructions
- Deterministic constructions based on coding/finite fields etc. give  $k \le C_0 \sqrt{n}$

ICM - p.33/3

#### **Computational Issues**

We have seen three competing issues: (i) optimality of the sparsity level k, (ii) number of computations to decode, (iii) stability

ICM - n.34/

#### **Computational Issues**

We have seen three competing issues: (i) optimality of the sparsity level k, (ii) number of computations to decode, (iii) stability

ICM - p.34/3

### **Computational Issues**

- We have seen three competing issues: (i) optimality of the sparsity level k, (ii) number of computations to decode, (iii) stability
- It is not yet clear exactly how these demands play against one another
- Theoretical Computer Science: Gilbert, Muthukrishnan, Strauss, and many others

ICM - p.34/3





ICM - p.35/3

- How to sense analog signals?
- Discrete to Analog

ICM - p.35/3

- How to sense analog signals?
- Discrete to Analog
- Can we build it: circuit implementation?

- How to sense analog signals?
- Discrete to Analog
- Can we build it: circuit implementation?
- In certain contexts there are already impressive results: Tomography (Candes)

ICM - p.35/

#### **Discrete Sensing**

- **.**  $x \in \mathbb{R}^N$  with N large
- We are able to ask n non-adaptive questions about x
- Question means inner product  $v \cdot x$  with  $v \in \mathbb{R}^N$  called sample
- Any such sampling is given by is an n × N matrix Φ : the entries in y = Φx are the answers to our questions

ICM - p.6/3

- How to sense analog signals?
- Discrete to Analog
- Can we build it: circuit implementation?
- In certain contexts there are already impressive results: Tomography (Candes)

ICM - p.35/

Web site on Compressed Sensing: Rice ECE

### **Discrete Sensing**

- $x \in \mathbb{R}^N$  with N large
- We are able to ask n non-adaptive questions about x
- Question means inner product  $v \cdot x$  with  $v \in \mathbb{R}^N$  called sample
- Any such sampling is given by is an n × N matrix Φ : the entries in y = Φx are the answers to our questions
- We are interested in the good / best matrices Φ, i.e. what are the best questions to ask??
- Here good roughly means that the samples  $y = \Phi x$ contain enough information to approximate x well



### **Discrete Sensing**

- $x \in \mathbb{R}^N$  with N large
- We are able to ask n non-adaptive questions about x
- Question means inner product  $v \cdot x$  with  $v \in \mathbb{R}^N$  called sample
- Any such sampling is given by is an n × N matrix Φ : the entries in y = Φx are the answers to our questions
- Here good roughly means that the samples  $y = \Phi x$ contain enough information to approximate x well
- Two issues: (i) Enough information in y; (ii) How to extract this information: Decoder

ICM - p.6/3

ICM - p.7/3

• Since  $\Phi : \mathbb{R}^N \to \mathbb{R}^n$  many x give the same measurements y

- Since Φ : ℝ<sup>N</sup> → ℝ<sup>n</sup> many x give the same measurements y
- $\mathcal{N} := \{\eta : \Phi \eta = 0\}$  the null space of  $\Phi \dim(\mathcal{N}) \ge N n$

ICM - p.7/3

- Since Φ : ℝ<sup>N</sup> → ℝ<sup>n</sup> many x give the same measurements y
- $\mathcal{N} := \{\eta : \Phi \eta = 0\}$  the null space of  $\Phi \dim(\mathcal{N}) \ge N n$

ICM - p.7/3

 $\mathcal{F}(y) := \{x : \Phi x = y\} = x_0 + \mathcal{N} \text{ for any } x_0 \in \mathcal{F}(y)$ 



- Since  $\Phi : \mathbb{R}^N \to \mathbb{R}^n$  many x are encoded with same y
- $\mathcal{N} := \{\eta : \Phi \eta = 0\}$  the null space of  $\Phi$
- $\mathcal{F}(y) := \{x : \Phi x = y\} = x_0 + \mathcal{N} \text{ for any } x_0 \in \mathcal{F}(y)$
- The hyperplanes  $\mathcal{F}(y)$  with  $y \in \mathbb{R}^n$  stratify  $\mathbb{R}^N$
- Decoder is any (possibly nonlinear) mapping  $\Delta$  from  $\mathbb{R}^n \to \mathbb{R}^N$

- Since  $\Phi : \mathbb{R}^N \to \mathbb{R}^n$  many x are encoded with same y
- $\mathcal{N} := \{\eta : \Phi \eta = 0\}$  the null space of  $\Phi$
- $\mathcal{F}(y) := \{x : \Phi x = y\} = x_0 + \mathcal{N} \text{ for any } x_0 \in \mathcal{F}(y)$
- The hyperplanes  $\mathcal{F}(y)$  with  $y \in \mathbb{R}^n$  stratify  $\mathbb{R}^N$
- Decoder is any (possibly nonlinear) mapping △ from  $\mathbb{R}^n \to \mathbb{R}^N$

1CM - 0.9/3

•  $\bar{x} := \Delta(\Phi(x))$  is our approximation to x from the information extracted

# **Many Settings**

ICM - p.3/35

- Numerical PDEs
- Data Fitting
- Statistical Estimation
- Encoding/Compression
- Compressed Sensing

- Since  $\Phi : \mathbb{R}^N \to \mathbb{R}^n$  many x are encoded with same y
- $\mathcal{N} := \{\eta : \Phi \eta = 0\}$  the null space of  $\Phi$
- $\mathcal{F}(y) := \{x : \Phi x = y\} = x_0 + \mathcal{N} \text{ for any } x_0 \in \mathcal{F}(y)$
- The hyperplanes  $\mathcal{F}(y)$  with  $y \in \mathbb{R}^n$  stratify  $\mathbb{R}^N$
- Decoder is any (possibly nonlinear) mapping  $\Delta$  from  $\mathbb{R}^n \to \mathbb{R}^N$

•  $\bar{x} := \Delta(\Phi(x))$  is our approximation to x from the information extracted

Pessimism: all  $x \in \mathcal{F}(y)$  are approximated by the same  $\bar{x}$ 

ICM - p.9/3



 With no additional information about x it is doubtful we can say anything

ICM - p.10/

With no additional information about x it is doubtful we can say anything

1CM - p.10

Fortunately the x we are interested in have structure

- With no additional information about x it is doubtful we can say anything
- Fortunately the x we are interested in have structure
- Typically x can be well represented by sparse linear combination of certain building blocks - for our purposes these building blocks are a basis

ICM - P

- With no additional information about x it is doubtful we can say anything
- Fortunately the x we are interested in have structure
- Typically x can be well represented by sparse linear combination of certain building blocks - for our purposes these building blocks are a basis
- In some(many) problems we do not necessarily know the right basis

ICM - D

- With no additional information about x it is doubtful we can say anything
- Fortunately the x we are interested in have structure
- Typically x can be well represented by sparse linear combination of certain building blocks - for our purposes these building blocks are a basis
- In some(many) problems we do not necessarily know the right basis
- For the most part we shall assume the basis is known to us

ICM - D1

• To begin with we shall assume x is sparse with respect to the canonical basis on  $\mathbb{R}^N$ 

ICM- p.11/

- To begin with we shall assume x is sparse with respect to the canonical basis on IR<sup>N</sup>
- Any other basis could be handled by transformation (if the basis is known)

ICM - p.11/3

- To begin with we shall assume x is sparse with respect to the canonical basis on  $\mathbb{R}^N$
- Any other basis could be handled by transformation (if the basis is known)

ICM = D.1

- To begin with we shall assume x is sparse with respect to the canonical basis on R<sup>N</sup>
- Any other basis could be handled by transformation (if the basis is known)

1CM - D.J

• The support of x is  $supp(x) := \{i : x_i \neq 0\}$ 

## **Many Settings**

ICM - p.4/35

- Numerical PDEs
- Data Fitting
- Statistical Estimation
- Encoding/Compression
- Compressed Sensing

- To begin with we shall assume x is sparse with respect to the canonical basis on IR<sup>N</sup>
- Any other basis could be handled by transformation (if the basis is known)

ICM - D.II

- The support of x is  $supp(x) := \{i : x_i \neq 0\}$
- $\boldsymbol{\varSigma}_k := \{ x : \# \operatorname{supp}(\mathbf{x}) \le \mathbf{k} \}$

- To begin with we shall assume x is sparse with respect to the canonical basis on  $\mathbb{R}^N$
- Any other basis could be handled by transformation (if the basis is known)
- The support of x is  $supp(x) := \{i : x_i \neq 0\}$

•  $\Sigma_k := \{x : \# \operatorname{supp}(\mathbf{x}) \le \mathbf{k}\}$ 

• Note that  $\Sigma_k$  is a union of k dimensional subspaces:  $\Sigma_k = \bigcup_{\#(T)=k} X_T$  where  $X_T = \{x : \operatorname{supp}(x) \subset T\}$ 

ICM = 0.11
### **First Measure of Optimality**

- To begin with we shall assume x is sparse with respect to the canonical basis on  $\mathbb{R}^N$
- Any other basis could be handled by transformation (if the basis is known)
- The support of x is  $supp(x) := \{i : x_i \neq 0\}$

 $\Sigma_k := \{ x : \# \operatorname{supp}(\mathbf{x}) \le \mathbf{k} \}$ 

- Note that  $\Sigma_k$  is a union of k dimensional subspaces:  $\Sigma_k = \bigcup_{\#(T)=k} X_T$  where  $X_T = \{x : \operatorname{supp}(x) \subset T\}$
- First Question: Given k, N what is the smallest n for which there is (Φ, Δ) such each vector in Σ<sub>k</sub> is captured exactly Δ(Φ(x)) = x, x ∈ Σ<sub>k</sub>

ICM - p.11

### **First Measure of Optimality**

- To begin with we shall assume x is sparse with respect to the canonical basis on IR<sup>N</sup>
- Any other basis could be handled by transformation (if the basis is known)
- The support of x is  $supp(x) := \{i : x_i \neq 0\}$

 $\Sigma_k := \{ x : \# \operatorname{supp}(\mathbf{x}) \le \mathbf{k} \}$ 

- Note that  $\Sigma_k$  is a union of k dimensional subspaces:  $\Sigma_k = \bigcup_{\#(T)=k} X_T$  where  $X_T = \{x : \operatorname{supp}(x) \subset T\}$
- First Question: Given k, N what is the smallest n for which there is (Φ, Δ) such each vector in Σ<sub>k</sub> is captured exactly Δ(Φ(x)) = x, x ∈ Σ<sub>k</sub>

ICM = D1

• Answer n = 2k

•  $\Phi = [v_1, \ldots, v_N], v_1, \ldots, v_N$  columns of  $\Phi$ 



ICM - n

•  $\Phi = [v_1, \dots, v_N], v_1, \dots, v_N$  columns of  $\Phi$ • If *T* is a set of column indices

- $\Phi = [v_1, \ldots, v_N], v_1, \ldots, v_N$  columns of  $\Phi$
- If T is a set of column indices
- $\Phi_T = [v_{i_1}, \dots, v_{i_m}]$  is the  $n \times \#(T)$  submatrix of  $\Phi$  formed from the columns with index  $T = \{i_1, \dots, i_m\}$

- $\Phi = [v_1, \ldots, v_N], v_1, \ldots, v_N$  columns of  $\Phi$
- If T is a set of column indices
- Φ<sub>T</sub> = [v<sub>i1</sub>,..., v<sub>im</sub>] is the n × #(T) submatrix of Φ formed from the columns with index T = {i<sub>1</sub>,..., i<sub>m</sub>}
   Φ<sup>\*</sup><sub>T</sub>Φ<sub>T</sub> := (⟨v<sub>i</sub>, v<sub>j</sub>⟩)<sub>i,j∈T</sub>

- $\Phi = [v_1, \ldots, v_n], \quad v_1, \ldots, v_N \text{ columns of } \Phi$
- If T is a set of column indices
- Φ<sub>T</sub> = [v<sub>i1</sub>,..., v<sub>im</sub>] is the #(T) × n submatrix of Φ formed from the columns with index T = {i<sub>1</sub>,..., i<sub>m</sub>}
   Φ<sub>T</sub><sup>\*</sup>Φ<sub>T</sub> := (⟨v<sub>i</sub>, v<sub>j</sub>⟩)<sub>i,j∈T</sub> of size #(T) × #(T)

Theorem: If  $\Phi$  is any  $n \times N$  matrix and  $2k \le n$ , then the following are equivalent:

(i) There is a  $\Delta$  such that  $\Delta(\Phi(x)) = x$ , for all  $x \in \Sigma_k$ , (ii)  $\Sigma_{2k} \cap \mathcal{N}(\Phi) = \{0\}$ , (iii) For any set T with #T = 2k, the matrix  $\Phi_T$  has rank 2k. (iv) For any set T with #T = 2k, the  $2k \times 2k$  matrix  $\Phi_T^* \Phi_T$  is invertible: all its eigenvalues are positive.

# **Optimal Matrices**

Given k can we construct matrices 

of size 2k × N with the properties of the theorem?

ICM - p.14/3

### **Many Settings**

- Numerical PDEs
- Data Fitting
- Statistical Estimation
- Encoding/Compression
- Compressed Sensing
- Signal Processing: Searching for better ways to sample signals than Shannon-Nyquist Theory

ICM - p.4/35

# **Optimal Matrices**

- Given k can we construct matrices 
  of size 2k × N with the properties of the theorem?
- We need N vectors in IR<sup>2k</sup> such that any 2k of them are linearly independent

ICM - n.14i

# **Optimal Matrices**

- We need N vectors in IR<sup>2k</sup> such that any 2k of them are linearly independent
- Vandermonde matrix. Choose  $x_1 < x_2 < \cdots < x_N$

# **Naive Decoding**

ICM - p.15/

 $\Delta(y) := \underset{z \in \Sigma_{k}}{\operatorname{Argmin}} \|y - \Phi(z)\|_{\ell_{2}^{n}}$   $X_{T} := \{z : \operatorname{supp}(z) \subset T\}$   $x_{T} := \underset{z \in X_{T}}{\operatorname{Argmin}} \|y - \Phi z\|_{\ell_{2}^{n}} \rightarrow x_{T} = [\Phi_{T}^{*}\Phi_{T}]^{-1}\Phi_{T}y$   $T^{*} := \operatorname{Argmin}_{\#(T)=k} \|y - \Phi(x_{T})\|_{\ell_{2}^{n}}$   $\Delta(y) := x_{T}.$ 

ICM - p.16

Have we solved our first problem?
None of us will be alive when the decoding is finished

Have we solved our first problem?
None of us will be alive when the decoding is finished
Moreover, the decoding is also unstable

 $ICM - p \, 160$ 

- Have we solved our first problem?
- None of us will be alive when the decoding is finished
- Moreover, the decoding is also unstable
- The first problem has an easy fix. We can take the first 2k rows of the discrete Fourier matrix and build a decoder which uses only  $O(N + k^3)$  operations:

- Have we solved our first problem?
- None of us will be alive when the decoding is finished
- Moreover, the decoding is also unstable
- The first problem has an easy fix. We can take the first 2k rows of the discrete Fourier matrix and build a decoder which uses only O(N + k<sup>3</sup>) operations:
- However the stability problem is more substantial no quick fix

ICM - p.16/3

- Have we solved our first problem?
- None of us will be alive when the decoding is finished
- Moreover, the decoding is also unstable
- The first problem has an easy fix. We can take the first 2k rows of the discrete Fourier matrix and build a decoder which uses only  $O(N + k^3)$  operations:
- However the stability problem is more substantial no quick fix
- Suppose we had any matrix  $\Phi$  and we knew the support T of x then  $x = x_T = [\Phi_T^* \Phi_T]^{-1} \Phi_T y$

ICM - p.16

- Have we solved our first problem?
- None of us will be alive when the decoding is finished
- Moreover, the decoding is also unstable
- The first problem has an easy fix. We can take the first 2k rows of the discrete Fourier matrix and build a decoder which uses only  $O(N + k^3)$  operations:
- However the stability problem is more substantial no quick fix
- Suppose we had any matrix  $\Phi$  and we knew the support T of x then  $x = x_T = [\Phi_T^* \Phi_T]^{-1} \Phi_T y$

Candes-Romberg-Tao; Donoho: Compressed Sensing

ICM - p.17/3

# **Many Settings**

- Numerical PDEs
- Data Fitting
- Statistical Estimation
- Encoding/Compression
- Compressed Sensing
- Signal Processing: Searching for better ways to sample signals than Shannon-Nyquist Theory

ICM-p.4/3

Candes-Romberg-Tao; Donoho: Compressed Sensing
 Two important discoveries: good matrices, decoding

- Candes-Romberg-Tao; Donoho: Compressed Sensing
- Two important discoveries: good matrices, decoding
- Restricted Isometry Property (RIP) of order k: There exists  $0 < \delta = \delta_k < 1$  such that the eigenvalues of  $\Phi_T^* \Phi_T$ are in  $[1 - \delta, 1 + \delta]$  whenever #(T) = k

- Candes-Romberg-Tao; Donoho: Compressed Sensing
- Two important discoveries: good matrices, decoding
- Restricted Isometry Property (RIP) of order k: There exists  $0 < \delta = \delta_k < 1$  such that the eigenvalues of  $\Phi_T^* \Phi_T$  are in  $[1 \delta, 1 + \delta]$  whenever #(T) = k

- Candes-Romberg-Tao; Donoho: Compressed Sensing
- Two important discoveries: good matrices, decoding
- Restricted Isometry Property (RIP) of order k: There exists  $0 < \delta = \delta_k < 1$  such that the eigenvalues of  $\Phi_T^* \Phi_T$  are in  $[1 \delta, 1 + \delta]$  whenever #(T) = k

ICM - p.1

Equivalently:

 $(1-\delta)\|x\|_{\ell_2^N}^2 \le \|\Phi(x)\|_{\ell_2^n}^2 \le (1+\delta)\|x\|_{\ell_2^N}^2, \quad x \in \Sigma_k$ 

- Candes-Romberg-Tao; Donoho: Compressed Sensing
- Two important discoveries: good matrices, decoding
- Restricted Isometry Property (RIP) of order k: There exists  $0 < \delta = \delta_k < 1$  such that the eigenvalues of  $\Phi_T^* \Phi_T$  are in  $[1 \delta, 1 + \delta]$  whenever #(T) = k
- Equivalently:

 $(1-\delta)\|x\|_{\ell_{\lambda}^{N}}^{2} \leq \|\Phi(x)\|_{\ell_{\lambda}^{n}}^{2} \leq (1+\delta)\|x\|_{\ell_{\lambda}^{N}}^{2}, \quad x \in \Sigma_{k}$ 

• Decode by  $\ell_1$  minimization

 $\Delta(y) := \inf_{x \in \mathcal{F}(y)} \|x\|_{\ell_1^N}$ 

ICM - p.1773

- Candes-Romberg-Tao; Donoho: Compressed Sensing
- Two important discoveries: good matrices, decoding
- Restricted Isometry Property (RIP) of order k: There exists 0 < δ = δ<sub>k</sub> < 1 such that the eigenvalues of Φ<sup>\*</sup><sub>T</sub>Φ<sub>T</sub> are in [1 δ, 1 + δ] whenever #(T) = k
- Equivalently:

 $(1-\delta) \|x\|_{\ell_{2}^{N}}^{2} \leq \|\Phi(x)\|_{\ell_{2}^{n}}^{2} \leq (1+\delta) \|x\|_{\ell_{2}^{N}}^{2}, \quad x \in \Sigma_{k}$ 

-

Decode by l<sub>1</sub> minimization

 $\Delta(y) := \inf_{x \in \mathcal{F}(y)} \|x\|_{\ell_1^N}$ 

ICM - P.

# $\ell_1$ ball meets the set $\mathcal{F}(y)$



ICM - p.18

- Candes-Romberg-Tao; Donoho: Compressed Sensing
  - Two important discoveries: good matrices, decoding
- Restricted Isometry Property (RIP) of order k: There exists 0 < δ = δ<sub>k</sub> < 1 such that</p>

 $(1-\delta) \|x\|_{\ell_{2}^{N}}^{2} \leq \|\Phi(x)\|_{\ell_{2}^{n}}^{2} \leq (1+\delta) \|x\|_{\ell_{2}^{N}}^{2}, \quad x \in \Sigma_{k}$ 

- Equivalently the eigenvalues of  $\Phi_T^* \Phi_T$  are in  $[1 \delta, 1 + \delta]$
- Decode by l<sub>1</sub> minimization

 $-\Delta(y) := \inf_{x \in \mathcal{F}(y)} \|x\|_{\ell_1^N}$ 

Candes-Tao: If Φ satisfies the RIP of order 3k then given any x ∈ Σk we have Δ(Φ(x)) = x for the ℓ1 minimization decoder. Moreover, the decoding is stable

ICM - p. 19/

- Candes-Romberg-Tao; Donoho: Compressed Sensing
- Two important discoveries: good matrices, decoding
- Restricted Isometry Property (RIP) of order k: There exists 0 < δ = δ<sub>k</sub> < 1 such that</p>

 $(1-\delta)\|x\|_{\ell_{2}^{N}}^{2} \leq \|\Phi(x)\|_{\ell_{2}^{n}}^{2} \leq (1+\delta)\|x\|_{\ell_{2}^{N}}^{2}, \quad x \in \Sigma_{k}$ 

- Equivalently the eigenvalues of  $\Phi_T^* \Phi_T$  are in  $[1 \delta, 1 + \delta]$
- Decode by l<sub>1</sub> minimization

 $\Delta(y) := \inf_{x \in \mathcal{F}(y)} \|x\|_{\ell_1^N}$ 

Candes-Tao: If Φ satisfies the RIP of order 3k then given any x ∈ Σk we have Δ(Φ(x)) = x for the ℓ1 minimization decoder. Moreover, the decoding is stable

ICM - p.19

How can we build matrices that satisfy RIP for the largest value of k

ICM - p.20/3

# **Many Settings**

- Numerical PDEs
- Data Fitting
- Statistical Estimation
- Encoding/Compression
- Compressed Sensing
- Signal Processing: Searching for better ways to sample signals than Shannon-Nyquist Theory

ICM - p.4/3

- Audience Friendly: Easy to digest
- Interfaces many areas of mathematics: Functional Analysis, Approximation, Probability, Theoretical Computer Science ...

- How can we build matrices that satisfy RIP for the largest value of k
- Given n, N we can construct such matrices for any k ≤ c<sub>0</sub>n/log(N/n)

ICM-p.20/3

- How can we build matrices that satisfy RIP for the largest value of k
- Given n, N we can construct such matrices for any k ≤ c<sub>0</sub>n/log(N/n)
- The additional log(N/n) is the price we pay for stability

ICM - p.20/3

● How can we construct such Φ?

- How can we build matrices that satisfy RIP for the largest value of k
- Given n, N we can construct such matrices for any k ≤ c<sub>0</sub>n/log(N/n)
- The additional log(N/n) is the price we pay for stability
- How can we construct such
- We want to create a lot of vectors v<sub>1</sub>,..., v<sub>N</sub> in IR<sup>n</sup> such that any choice of k of them are far from being linearly dependent

ICM - p.20/

- How can we build matrices that satisfy RIP for the largest value of k
- Given n, N we can construct such matrices for any k ≤ c<sub>0</sub>n/log(N/n)
- The additional log(N/n) is the price we pay for stability
- We want to create a lot of vectors v<sub>1</sub>,..., v<sub>N</sub> in IR<sup>n</sup> such that any choice of k of them are far from being linearly dependent

ICM - p.20/

### **Three constructions**

We choose at random N vectors from the unit sphere in R<sup>n</sup> and use these as the columns of Φ

ICM - p.21/3
- We choose each entry of 
   independently and at random from the Gaussian distribution with mean 0 and variance n<sup>-1</sup>

ICM - p.21/3

- We choose at random N vectors from the unit sphere in R<sup>n</sup> and use these as the columns of Φ

ICM - p.21/3

- We choose at random N vectors from the unit sphere in R<sup>n</sup> and use these as the columns of Φ

CM - p.21/

 We use Bernouli process and create a matrix with entries -1,1 (or 0, 1)

- We choose at random N vectors from the unit sphere in R<sup>n</sup> and use these as the columns of Φ
- We choose each entry of 
   independently and at random from the Gaussian distribution with mean 0 and variance n<sup>-1</sup>
- We use Bernouli process and create a matrix with entries -1,1 (or 0,1)

ICM - p.210

- We choose at random N vectors from the unit sphere in
   IR<sup>n</sup> and use these as the columns of Φ
- We use Bernouli process and create a matrix with entries -1,1 (or 0,1)

ICM - p.21/3

# **Discrete Sensing**

ICM - p.6/3

 $\boldsymbol{x} \in \mathbb{R}^N$  with N large

- We choose at random N vectors from the unit sphere in R<sup>\*\*</sup> and use these as the columns of Φ
- We choose each entry of 
   independently and at random from the Gaussian distribution with mean 0 and variance n<sup>-1</sup>
- We use Bernouli process and create a matrix with entries -1,1 (or 0,1)
- Algorithm is constructive (not probabilistic) once we find a ⊕. Probability is only used to prove existence of ⊕

ICM - p.2

- We choose at random N vectors from the unit sphere in R<sup>n</sup> and use these as the columns of Φ
- We choose each entry of 
   independently and at random from the Gaussian distribution with mean 0 and variance n<sup>-1</sup>
- We use Bernouli process and create a matrix with entries -1,1 (or 0,1)
- Algorithm is constructive (not probabilistic) once we find a Φ. Probability is only used to prove existence of Φ

ICM - p.21/3

ICM - p.22/3

■ Let  $\Phi(\omega) = (\phi_{i,j}(\omega)), \omega \in \Omega$ , be random matrices

■ Let  $\Phi(\omega) = (\phi_{i,j}(\omega)), \omega \in \Omega$ , be random matrices

Here each entry \u03c6<sub>i,j</sub> is an independent realization of some fixed random variable r with mean zero and variance 1/n

ICM - p.22/3

- Let  $\Phi(\omega) = (\phi_{i,j}(\omega)), \omega \in \Omega$ , be random matrices
- Here each entry \u03c6<sub>i,j</sub> is an independent realization of some fixed random variable r with mean zero and variance 1/n

ICM - p.22/3

• Trivially we have  $E(\|\Phi(\omega)x\|_{\ell_{1}^{m}}^{2}) = \|x\|_{\ell_{1}^{m}}^{2}$ 

- Let  $\Phi(\omega) = (\phi_{i,j}(\omega)), \omega \in \Omega$ , be random matrices
- Here each entry \u03c6<sub>i,j</sub> is an independent realization of some fixed random variable r with mean zero and variance 1/n

ICM - p.22/3

• Trivially we have  $E(\|\Phi(\omega)x\|_{\ell_{2}}^{2}) = \|x\|_{\ell_{2}}^{2}$ 

## Lazy man Proof

Theorem (Baraniuk, Davenport, DeVore, Wakin) Given  $c_0$  there is a  $c_1 > 0$  such that with probability  $1 - e^{-c_1 n}$ , the matrix  $\Phi(\omega)$  satisfies RIP of order k for all  $k \le c_0 n / \log(N/n)$ 

- We find a net of points P which cover the unit sphere in Σ<sub>k</sub> to accuracy δ/4
- Using the concentration inequality, we see that with high probability the draw of Φ = Φ(ω) satisfies

 $(1 - \delta/2) \|q\|_{\ell_2^N} \le \|\Phi(q)\|_{\ell_2^n} \le (1 + \delta/2) \|q\|_{\ell_2^N}, \quad q \in \mathcal{P}$ 

Extend this to all x ∈ Σ<sub>k</sub> by a boot strapping estimate: Given x with ||x||<sub>ℓN</sub> = 1 find q such that ||x − q||<sub>ℓN</sub> ≤ δ/4

 $\|\Phi(x)\|_{\ell_2^n} \le \|\Phi(x-q)\|_{\ell_2^n} + \|\Phi(q)\|_{\ell_2^n} \le M\delta/4 + 1 + \delta/2 - \|CM - p\|_{\ell_2^n} \le M\delta/4 + 1 + \delta/2 - \|CM - p\|_{\ell_2^n} \le M\delta/4 + 1 + \delta/2 - \|CM - p\|_{\ell_2^n} \le M\delta/4 + 1 + \delta/2 - \|CM - p\|_{\ell_2^n} \le M\delta/4 + 1 + \delta/2 - \|CM - p\|_{\ell_2^n} \le M\delta/4 + 1 + \delta/2 - \|CM - p\|_{\ell_2^n} \le M\delta/4 + 1 + \delta/2 - \|CM - p\|_{\ell_2^n} \le M\delta/4 + 1 + \delta/2 - \|CM - p\|_{\ell_2^n} \le M\delta/4 + 1 + \delta/2 - \|CM - p\|_{\ell_2^n} \le M\delta/4 + 1 + \delta/2 - \|CM - p\|_{\ell_2^n} \le M\delta/4 + 1 + \delta/2 - \|CM - p\|_{\ell_2^n} \le M\delta/4 + 1 + \delta/2 - \|CM - p\|_{\ell_2^n} \le M\delta/4 + 1 + \delta/2 - \|CM - p\|_{\ell_2^n} \le M\delta/4 + 1 + \delta/2 - \|CM - p\|_{\ell_2^n} \le M\delta/4 + 1 + \delta/2 - \|CM - p\|_{\ell_2^n} \le M\delta/4 + 1 + \delta/2 - \|CM - p\|_{\ell_2^n} \le M\delta/4 + 1 + \delta/2 - \|CM - p\|_{\ell_2^n} \le M\delta/4 + 1 + \delta/2 - \|CM - p\|_{\ell_2^n} \le M\delta/4 + 1 + \delta/2 - \|CM - p\|_{\ell_2^n} \le M\delta/4 + 1 + \delta/2 - \|CM - p\|_{\ell_2^n} \le M\delta/4 + 1 + \delta/2 - \|CM - p\|_{\ell_2^n} \le M\delta/4 + \|CM - p\|_{\ell_2^n} \le \|CM - p\|$ 

## Lazy man Proof

Theorem (Baraniuk, Davenport, DeVore, Wakin) Given  $c_0$  there is a  $c_1 > 0$  such that with probability  $1 - e^{-c_1 n}$ , the matrix  $\Phi(\omega)$  satisfies RIP of order k for all  $k \le c_0 n / \log(N/n)$ 

- We find a net of points P which cover the unit sphere in Σ<sub>k</sub> to accuracy δ/4
- Using the concentration inequality, we see that with high probability the draw of  $\Phi = \Phi(\omega)$  satisfies

 $(1 - \delta/2) \|q\|_{\ell_{2}^{N}} \le \|\Phi(q)\|_{\ell_{2}^{n}} \le (1 + \delta/2) \|q\|_{\ell_{2}^{N}}, \quad q \in \mathcal{P}$ 

Extend this to all x ∈ Σ<sub>k</sub> by a boot strapping estimate: Given x with ||x||<sub>ℓN</sub> = 1 find q such that ||x − q||<sub>ℓN</sub> ≤ δ/4

 $\|\Phi(x)\|_{\ell_2^n} \le \|\Phi(x-q)\|_{\ell_2^n} + \|\Phi(q)\|_{\ell_2^n} \le M\delta/4 + 1 + \delta/2 - \frac{1}{100}$ 

# Universality

- Suppose we have a collection of basis B := {B}
- $\#(\mathcal{B}) \leq Ce^{cn}$
- This means this one 
   will capture sparsity with respect to any and all of these bases

ICM - p.24/3

However to decode we need to know the basis

# Universality

- Suppose we have a collection of basis B := {B}
- $#(\mathcal{B}) \leq Ce^{cn}$

ICM - p.24/3

However to decode we need to know the basis

# **Discrete Sensing**

•  $x \in \mathbb{R}^N$  with N large

We are able to ask n non-adaptive questions about x

ICM - p.6/3

# Universality

- Suppose we have a collection of basis  $\mathcal{B} := \{B\}$
- $\#(\mathcal{B}) \leq Ce^{cn}$
- This means this one 
   will capture sparsity with respect to any and all of these bases

ICM - p.24/3

However to decode we need to know the basis

# **Model II: Compressible Signals**

- The sparse signal classes do not represent real signals: signals will typically have all entries nonzero but most will be small
- A compressible signal x is one that can be approximated well by elements from  $\Sigma_k$ :  $\sigma_k(x)_X := \inf_{z \in \Sigma_k} ||x - z||_X$
- Typical signal classes are  $U(\ell_p^N)$  and typical  $X = \ell_q^N$  $\|x\|_{\ell_p^N} := \left(\sum_{i=1}^N |x_i|^p\right)^{1/p}$

ICM - p.25/3

- If  $x \in U(\ell_p^N)$  then  $\sigma_k(x)_{\ell_q^N} \leq k^{1/q-1/p}$ , p < q
- Example (q = 2, p = 1):  $\sigma_k(x)_{\ell_2^N} \le k^{-1/2}$

# **Model II: Compressible Signals**

- The sparse signal classes do not represent real signals: signals will typically have all entries nonzero but most will be small
- A compressible signal x is one that can be approximated well by elements from Σ<sub>k</sub>:  $\sigma_k(x)_X := \inf_{z \in \Sigma_k} \|x z\|_X$
- Typical signal classes are  $U(\ell_p^N)$  and typical  $X = \ell_q^N$  $\|x\|_{\ell_p^N} := \left(\sum_{i=1}^N |x_i|^p\right)^{1/p}$

ICM - p.25/3

- If  $x \in U(\ell_p^N)$  then  $\sigma_k(x)_{\ell_q^N} \leq k^{1/q-1/p}$ , p < q
- Example (q = 2, p = 1):  $\sigma_k(x)_{\ell_2^N} \le k^{-1/2}$

## **Optimality on Models II**

Let K be a compact set in IR<sup>N</sup>
Best performance on the class K in norm || · ||<sub>X</sub>

$$E_n(K)_X := \inf_{(\Phi,\Delta)\in\mathcal{A}_n} \sup_{x\in K} \|x - \Delta(\Phi(x))\|_X$$

• Here  $\mathcal{A}_n = \{(\Phi, \Delta) : \Phi \text{ is } n \times N\}$ 

• The pair  $(\Phi, \Delta)$  is near optimal if

 $\sup_{x \in K} \|x - \Delta(\Phi(x))\|_X \le C_0 E_n(K)_X$ 

ICM - p.26/3

## **Optimality on Models II**

Let K be a compact set in IR<sup>N</sup>
Best performance on the class K in norm || · ||<sub>X</sub>

$$E_n(K)_X := \inf_{(\Phi,\Delta)\in\mathcal{A}_n} \sup_{x\in K} \|x - \Delta(\Phi(x))\|_X$$

• Here  $\mathcal{A}_n = \{(\Phi, \Delta) : \Phi \text{ is } n \times N\}$ 

• The pair  $(\Phi, \Delta)$  is near optimal if

 $\sup_{x \in K} \|x - \Delta(\Phi(x))\|_X \le C_0 E_n(K)_X$ 

ICM - p.26/3

# **Optimality on** $\ell_p^N$ classes

• The asymptotic behavior of  $E_n(K)_X$  is known for all  $K = U(\ell_p^N)$  in all  $X = \ell_q^N$ 

- Solved in 1970's and 1980's in Approximation Theory and Finite Dimensional Geometry
- Kashin, Gluskin main players
- Example (p = 1, q = 2)

$$C_0 \sqrt{\frac{\log(N/n)}{n}} \le E_n (U(\ell_1^N))_{\ell_2^N} \le C_1 \sqrt{\frac{\log(N/n)}{n}}$$

- These results do not provide practical encoding/decoding schemes
- Candes-Tao , Donoho show that RIP +  $l_1$  minimization give near optimal performance for q = 2, p ≤ 1

ICM - p.27/3

## Instance-Optimal

We say (Φ, Δ) is Instance-Optimal of order k for X if for an absolute constant C > 0 (independent of k, n, N)

 $\|x - \Delta(\Phi(x))\|_X \le C\sigma_k(x)_X$ 

- We will be interested in  $X = \ell_q^N$
- Problem: for a given X and size n × N find the largest values of k for which we have instance-optimality and the encoder-decoder pairs (Φ, Δ) which admit these values of k
- Cohen-Dahmen-DeVore solve the instance-optimal problem for all 1 ≤ q ≤ 2

ICM - p.28/3

## Instance-Optimal

We say (Φ, Δ) is Instance-Optimal of order k for X if for an absolute constant C > 0 (independent of k, n, N)

 $\|z - \Delta(\Phi(x))\|_X \le C\sigma_k(x)_X$ 

• We will be interested in  $X = \ell_q^N$ 

- Problem: for a given X and size n × N find the largest values of k for which we have instance-optimality and the encoder-decoder pairs (Φ, Δ) which admit these values of k
- Cohen-Dahmen-DeVore solve the instance-optimal problem for all 1 ≤ q ≤ 2

ICM - p.28/3

## **Instance-Optimal**

We say (Φ, Δ) is Instance-Optimal of order k for X if for an absolute constant C > 0 (independent of k, n, N)

 $||x - \Delta(\Phi(x))||_X \le C\sigma_k(x)_X$ 

• We will be interested in  $X = \ell_q^N$ 

Problem: for a given X and size n × N find the largest values of k for which we have instance-optimality and the encoder-decoder pairs (Φ, Δ) which admit these values of k

Cohen-Dahmen-DeVore solve the instance-optimal problem for all 1 ≤ q ≤ 2

## **Good News**

Let X = ℓ<sub>1</sub><sup>N</sup> and let Φ satisfy RIP for 3k, i.e. δ<sub>3k</sub> < 1 then there is a decoder such that (Φ, Δ) is instance optimal for k:

$$\|x - \Delta(\Phi(x))\|_{\ell_1^N} \le C_0 \sigma_k(x)_{\ell_1^N}$$

- Given n we can have instance optimality if k ≤ c<sub>0</sub>n/log(N/n)
- Bonus: Decoding can be done by l<sub>1</sub> Minimization
- Although not explicitly stated there this result is easily derived from the work of Candes-Tao

## **Discrete Sensing**

- $x \in \mathbb{R}^N$  with N large
- We are able to ask n non-adaptive questions about x
- Question means inner product  $v \cdot x$  with  $v \in \mathbb{R}^N$  called sample

## **Bad News**

- Let  $X = \ell_2^N$ , then in order to have instance optimality for k = 1 we need  $n \ge c_0 N$
- Here co depends on the instance optimality constant C
- OOPS: Instance Optimality is not a Viable Concept in

We saw that Instance-Optimality for (<sup>N</sup><sub>2</sub> is not viable)

. We saw that Instance-Optimality for  $\ell_2^N$  is not viable



. We saw that Instance-Optimality for  $\ell_2^N$  is not viable



- . We saw that Instance-Optimality for  $\ell_2^N$  is not viable
- Suppose  $\Phi(\omega)$  is a collection of random matrices
- We say this family satisfies RIP of order k with probability 1 - e if a random draw {Φ(ω)} will satisfy RIP of order k with probability 1 - e
- We say {Φ(ω)} is bounded with probability 1 − ε if given any x ∈ ℝ<sup>N</sup> with probability 1 − ε a random draw {Φ(ω)} will satisfy

 $\|\Phi(\omega)(x)\|_{\ell_2^N} \le C_0 \|x\|_{\ell_2^N}$ 

ICM - p.31/3

with  $C_0$  an absolute constant

- We saw that Instance-Optimality for C<sup>N</sup><sub>2</sub> is not viable
- Suppose  $\Phi(\omega)$  is a collection of random matrices
- We say this family satisfies RIP of order k with probability 1 - e if a random draw {Φ(ω)} will satisfy RIP of order k with probability 1 - e
- We say {Φ(ω)} is bounded with probability 1 − ε if given any x ∈ ℝ<sup>N</sup> with probability 1 − ε a random draw {Φ(ω)} will satisfy

 $\|\Phi(\omega)(x)\|_{\ell_2^N} \le C_0 \|x\|_{\ell_2^N}$ 

ICM - p.31/3

with  $C_0$  an absolute constant

## **Theorem:** Cohen-Dahmen-DeVore

If {Φ(ω)} satisfies RIP of order 3k and boundedness each with probability 1 − e then there are decoders Δ(ω) such that given any x ∈ ℓ<sub>2</sub><sup>N</sup> we have with probability 1 − 2e

 $||x - \Delta(\omega)\Phi(\omega)(x)||_{\ell_2^N} \le C_0 \sigma_k(x)_{\ell_2^N}$ 

ICM - p.32/3

## **Theorem: Cohen-Dahmen-DeVore**

• If  $\{\Phi(\omega)\}$  satisfies RIP of order 3k and boundedness each with probability  $1 - \epsilon$  then there are decoders  $\Delta(\omega)$ such that given any  $x \in \ell_2^N$  we have with probability  $1 - 2\epsilon$ 

 $\|x - \Delta(\omega)\Phi(\omega)(x)\|_{\ell_2^N} \le C_0 \sigma_k(x)_{\ell_2^N}$ 

ICM - p.32/3

Instance-optimality in probability
 Range of k is k ≤ c<sub>0</sub>n/log(N/n)

## **Theorem:** Cohen-Dahmen-DeVore

If  $\{\Phi(\omega)\}$  satisfies RIP of order 3k and boundedness each with probability  $1 - \epsilon$  then there are decoders  $\Delta(\omega)$ such that given any  $x \in \ell_2^N$  we have with probability  $1 - 2\epsilon$ 

 $\|x - \Delta(\omega)\Phi(\omega)(x)\|_{\ell_2^N} \le C_0 \sigma_k(x)_{\ell_2^N}$ 

- Instance-optimality in probability
- Range of k is  $k \le c_0 n / \log(N/n)$
- Decoder is the least squares minimization



# **Optimal Matrices**

 We have only built Optimal Matrices using probabilistic methods

ICM - p.33/3